



2027

Mrs Physics' Higher Physics Compendium ANSWERS



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Mostly Harmless

1 SUMMARY OF THE PHYSICS COURSE

The following material is taken from the Higher Course Specifications version 1.0 April 2018 produced by the SQA. <https://www.sqa.org.uk/sqa/47916.html>

There are three units to this course and an Assignment

1.1 SUMMARY OF OUR DYNAMIC UNIVERSE

The topics covered are:

-  motion – equations and graphs
-  forces, energy and power
-  collisions, explosions, and impulse
-  gravitation
-  special relativity
-  the expanding Universe

1.2 SUMMARY OF PARTICLES AND WAVES

The topics covered are:

-  forces on charged particles
-  the Standard Model
-  nuclear reactions
-  inverse square law
-  wave-particle duality
-  interference
-  spectra
-  refraction of light

1.3 SUMMARY OF ELECTRICITY

The topics covered are:

-  monitoring and measuring AC
-  current, potential difference, power, and resistance
-  electrical sources and internal resistance
-  capacitors
-  semiconductors and p-n junctions

There is also an assignment which must be completed.

COURSE OUTCOMES

No	CONTENT
1.	Uncertainties
eq	random uncertainty = $\frac{\text{max. value} - \text{min. value}}{\text{number of values}}$ or $\Delta R = \frac{R_{\text{max}} - R_{\text{min}}}{n}$
1.1	all measurements of physical quantities are liable to uncertainty
1.2	I can quantify and recognise scale reading, random and systematic uncertainties in a measured quantity.
1.3	I can express uncertainties in absolute or percentage form
1.4	random uncertainties arise when an experiment is repeated and slight variations occur.
1.5	scale reading uncertainty is a measure of how well an instrument scale can be read. Analogue device = $\pm \frac{1}{2}$ scale division Digital device = ± 1 in the last digit
1.6	scale reading uncertainty is an indication of how precisely a scale can be read.
1.7	random uncertainties can be reduced by taking repeated measurements.
1.8	systematic uncertainties occur when readings taken are either all too small or all too large.
1.9	systematic uncertainties can arise due to measurement techniques or experimental design.
1.10	the mean of a set of repeated measurements is the best estimate of the 'true' value of the quantity being measured.
1.11	when systematic uncertainties are present, they offset the mean value
1.12	when mean values are used, the approximate random uncertainty should be calculated.
1.13	I can correctly calculate, use and identify uncertainties during data analysis.
1.14	when an experiment is being undertaken and more than one physical quantity is measured, the quantity with the largest percentage uncertainty should be identified and this may often be used as a good estimate of the percentage uncertainty in the final numerical result of an experiment.

1.15	I can express the numerical result of an experiment in the form final value $\pm$ uncertainty. 1. <u>Find the mean</u> $\text{mean value} = \frac{\Sigma \text{results}}{\text{no. of observation}}$ This is the best estimate of the “true” value but not necessary the “true” value  2. <u>Find the approximate random uncertainty in the mean (absolute uncertainty)</u> $\text{random uncertainty} = \frac{\text{max. value} - \text{min. value}}{\text{number of values}}$ This can be written as $= \frac{\text{range}}{\text{no. of observation}}$ and it is sometimes referred to as <i>average deviation or absolute uncertainty</i>.  stop here and quote the result with an approx. random uncertainty MEAN $\pm$ approx. random uncertainty (UNITS) 3. <u>Find the percentage uncertainty.</u> $\text{percentage uncertainty} = \frac{\text{approximately random uncertainty}}{\text{mean value}} \times 100\% =$ $\text{percentage uncertainty} = \frac{\frac{\text{range}}{n}}{\text{mean value}} \times 100\%$  stop here and quote the result with a percentage uncertainty MEAN (UNITS) $\pm$ percentage uncertainty (%) Or (uncertainty in reading/reading)$\times$ 100%
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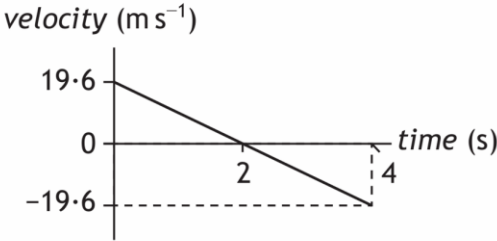
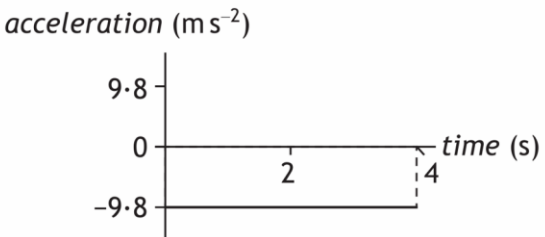
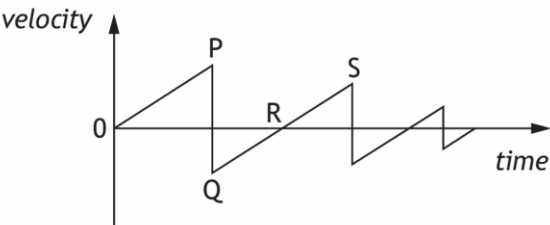
1.4 UNITS PREFIXES AND SCIENTIFIC NOTATION

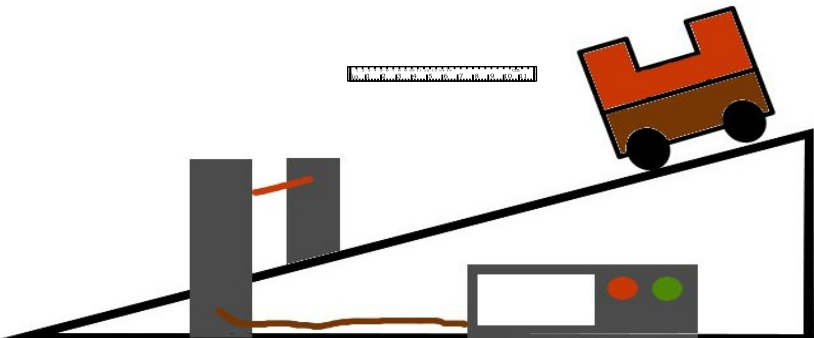
No	CONTENT
2.	Units, prefixes and scientific notation
2.1	I know the units for all of the physical quantities used in this unit. (see annotated relationships sheet)
2.2	I can use the prefixes: pico (p), nano (n), micro (μ), milli (m), kilo (k), mega (M), giga (G) and tera (T).

No	CONTENT																																								
	<table><tr><th>Prefix</th><th>Symbol</th><th>Multiple</th><th>Multiple in full</th></tr><tr><td>Tera</td><td>T</td><td>$\times 10^{12}$</td><td>$\times 1\,000\,000\,000\,000$</td></tr><tr><td>Giga</td><td>G</td><td>$\times 10^9$</td><td>$\times 1\,000\,000\,000$</td></tr><tr><td>Mega</td><td>M</td><td>$\times 10^6$</td><td>$\times 1\,000\,000$</td></tr><tr><td>Kilo</td><td>k</td><td>$\times 10^3$</td><td>$\times 1\,000$</td></tr><tr><td></td><td></td><td>$\times 1$</td><td>1</td></tr><tr><td>Milli</td><td>m</td><td>$\times 10^{-3}$</td><td>$\div 1\,000$</td></tr><tr><td>Micro</td><td>μ</td><td>$\times 10^{-6}$</td><td>$\div 1\,000\,000$</td></tr><tr><td>Nano</td><td>n</td><td>$\times 10^{-9}$</td><td>$\div 1\,000\,000\,000$</td></tr><tr><td>Pico</td><td>p</td><td>$\times 10^{-12}$</td><td>$\div 1\,000\,000\,000\,000$</td></tr></table> Above is a table of prefixes, which you will commonly find in Higher Physics. NB THE STANDARD UNIT FOR MASS IS THE KILOGRAM. Do not try changing it to grams! Watch out for ms which is milli seconds not metres per second!	Prefix	Symbol	Multiple	Multiple in full	Tera	T	$\times 10^{12}$	$\times 1\,000\,000\,000\,000$	Giga	G	$\times 10^9$	$\times 1\,000\,000\,000$	Mega	M	$\times 10^6$	$\times 1\,000\,000$	Kilo	k	$\times 10^3$	$\times 1\,000$			$\times 1$	1	Milli	m	$\times 10^{-3}$	$\div 1\,000$	Micro	μ	$\times 10^{-6}$	$\div 1\,000\,000$	Nano	n	$\times 10^{-9}$	$\div 1\,000\,000\,000$	Pico	p	$\times 10^{-12}$	$\div 1\,000\,000\,000\,000$
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2.3	I can give an appropriate number of significant figures when carrying out calculations. (This means that the final answer can have no more significant figures than the value with least number of significant figures used in the calculation). Find the number with the least significant figures given in the question. This should be the number of sig fig you quote in your answer. Do not round up too early. If you struggle change your calculator settings to SCI and use 3 sig fig, this usually works as a final answer.																																								
2.4	I can use scientific notation when large and small numbers are used in calculations.																																								

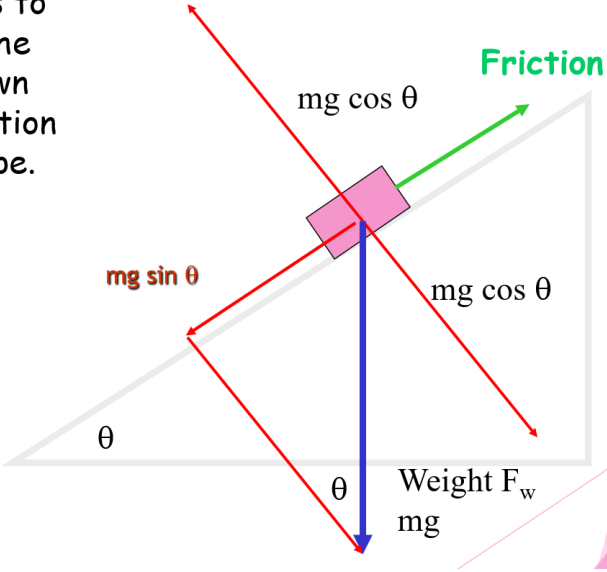
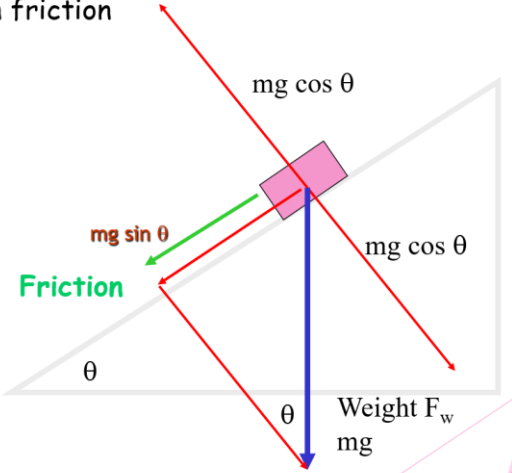
1.5 OUR DYNAMIC UNIVERSE

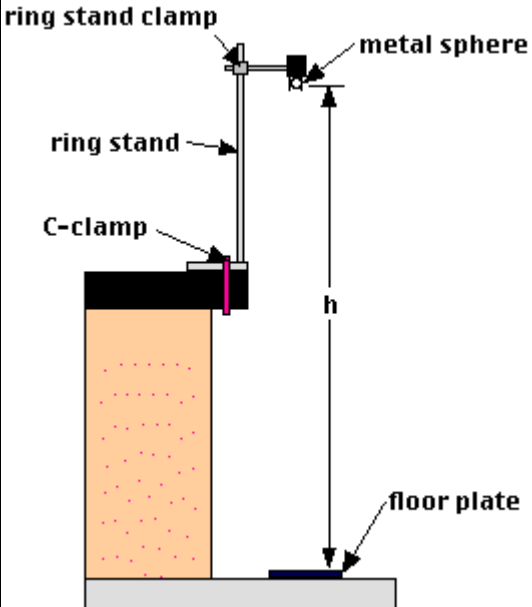
No	CONTENT	✓ x
3.	Equations of Motion	
Eq	$d = \overline{v}t$, $s = \overline{v}t$; $s = \frac{1}{2}(u + v)t$; $v = u + at$ $s = ut + \frac{1}{2}at^2$ $v^2 = u^2 + 2as$	
3.1	I can use the equations of motion to find distance, displacement, speed, velocity, and acceleration for objects with constant acceleration in a straight line. Remember s, v, a are vector quantities you must remember the direction, especially in the vertical component of projectile questions, that s will be negative, if a is negative and the object falls below it's starting point.	
3.2	I can interpret and draw motion-time graphs for motion with constant acceleration in a straight line, including graphs for bouncing objects and objects thrown vertically upwards.	

No	CONTENT	✓ x
	12 Sketch a v-t graph for an object thrown up in the air and caught on its return  • For earth the gradient should be 9.8 ms^{-2} • the initial velocity and time can vary • The initial and final vertical velocities should be constant if the ball is caught at the same height • The area under the graph should equal zero, as the bottom half is the negative displacement (return journey) • The area under the top half of the graph represents the max height reached • The gradient = acceleration = g = negative 	
	1 Sketch a a-t graph for an object thrown up in the air and caught on its return  • For earth the gradient should be zero • For Earth the value of $a = -9.8 \text{ ms}^{-2}$ • The area under the graph should equal the change in velocity, • The time depends on how long the object remains in the air	
	14 Sketch a v-t graph for an object dropped and allowed to bounce several times  • For Earth the gradient, $0P/QS$ should be equal and equal 9.8 ms^{-2} • the initial velocity is zero as dropped from rest • The gradient $PQ/ST \gg 0P/QS$ as this is the acceleration during the bounce and the rate of change of velocity is great. • The velocity at $P > S$ so after the bounce the ball must have lost E_k, the collision is inelastic 	
3.3	I know the interrelationship of displacement-time, velocity-time and acceleration- time graphs.	

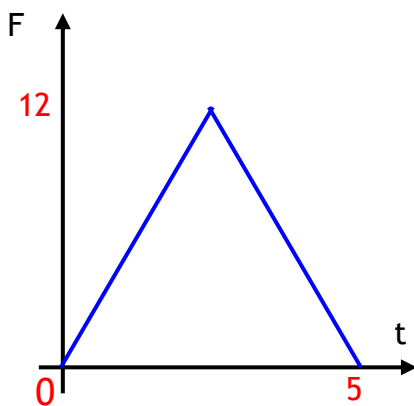
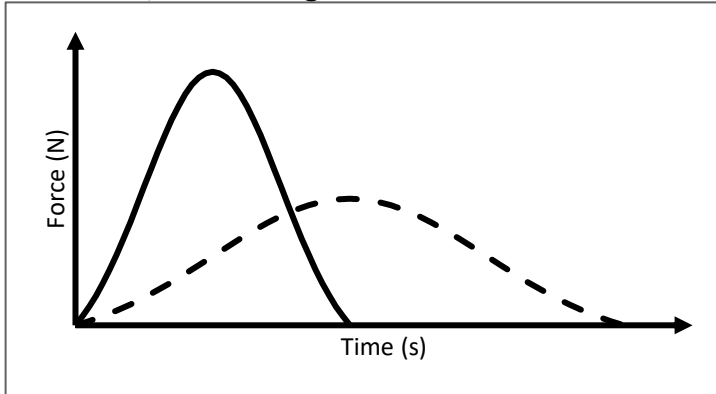
No	CONTENT	✓ x
3.4	I can calculate distance, displacement, speed, velocity, and acceleration from appropriate graphs (graphs restricted to constant acceleration in one dimension, inclusive of change of direction). Gradient of a v-t graph = acceleration Area under a v-t graph = displacement (or distance if you ignore the under the y=0 is negative and just add all the areas) Gradient of a s-t graph = velocity Area under a a-t graph = change in velocity	
	An acceleration of XXX means the velocity increases by $XXX \text{ m s}^{-1}$ every second	
3.5	<i>I can give a description of an experiment to measure the acceleration of an object down a slope</i>  Or use two light gates and a single mask Or if $u=0 \text{ ms}^{-1}$ then measure instantaneous speed at the bottom of the slope but time for the object to roll down the slope. To compensate for friction find the angle you have to lift the slope so that the trolley moves down the slope with 0 acceleration or at constant velocity. The rename this height zero and subtract this $a=0$ height from all other heights.	

4.	Forces, energy and power	
Eq	$W = mg$ $F = ma$ $E_w \text{ or } W = Fd$ $E_p = mgh$ $E_k = \frac{1}{2} mv^2$ $E = Pt$	
4.1	I can use vector addition and appropriate relationships to solve problems involving balanced and unbalanced forces, mass, acceleration and gravitational field strength.	
4.2	I know the effects of friction on a moving object (static and dynamic friction are not required) Friction always opposes motion, so is in the opposite direction to the unbalanced Force and direction of travel.	
4.3	I can identify and explain the effects of friction on moving objects. I do not need to use reference to static and dynamic friction. Friction always opposes motion, so always works against the unbalanced force. (check).	
4.4	I can identify and explain, in terms of forces an object moving with terminal velocity For an object travelling at terminal velocity the frictional forces balance any force causing a forward motion. The result is a constant velocity	
4.5	I can interpret and produce velocity-time graphs for a falling object when air resistance is taken into account.	
4.6	I can analyse motion using Newton's first and second laws.	

No	CONTENT	✓ x
4.7	I can use free body diagrams and appropriate relationships to solve problems involving friction and tension. Consider Tension as the balancing Force. To get the direction cut the object under tension and the way the object moves will be in the opposite direction to the tension (when it was present)	
4.8	I can resolve a vector into two perpendicular components. (Rec(hypotenuse,angle) X=adj, Y=opp)	
4.9	I can resolve the weight of an object on a slope into a component acting parallel (down the slope) and a component acting normal to the slope. The component of force acting down the slope is $mg \sin \theta$ The component of force acting into the slope is $mg \cos \theta$ is balanced by the reaction force from the slope. If there is friction its direction opposes motion, so If the object is travelling down the slope you have $mg \sin \theta$ down the slope and friction up the slope If the object is travelling up the slope you have $mg \sin \theta$ and friction down the slope so the acceleration (-ve) will be greater than the acceleration down the slope. Friction always acts to oppose motion. If the object is sliding down the slope, then friction must act up the slope.  Friction always acts to oppose motion. If the object being pushed up the slope then friction acts down the slope. 	

No	CONTENT	✓ x
4.10	I can use the principle of conservation of energy and appropriate relationships to solve problems involving work done, potential energy, kinetic energy and power. If there are no energy losses due to friction $E_w = Fd = mgh = \frac{1}{2}mv^2 = \frac{P}{t}$	
	 ring stand clamp metal sphere ring stand C-clamp h floor plate An experiment to measure the acceleration of a falling object.	

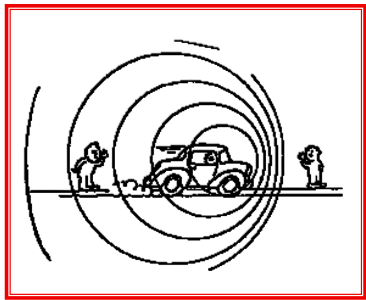
5.	Collisions and explosions	
Eq	$p = mv$ $Ft = mv - mu$ $E_k = \frac{1}{2}mv^2$	
5.1	I can use the principle of conservation of momentum and an appropriate relationship to solve problems involving the momentum, mass and velocity of objects interacting in one dimension. <u>Total momentum before (a collision) is equal to the total momentum after (a collision) in the absence of external forces.</u>	
5.2	I can explain the role in kinetic energy in determining whether a collision is described as elastic and inelastic collisions or in explosions. In ALL collisions TOTAL momentum is CONSERVED, TOTAL ENERGY is CONSERVED In an ELASTIC COLLISION= Kinetic energy is conserved In an INELASTIC COLLISION= Kinetic energy is lost	
5.3	I can use appropriate relationships to solve problems involving the total kinetic energy of systems of interacting objects. Total momentum before = total momentum after $m_1u_1 + m_2u_2 = m_2v_2 + m_1v_1$ $m_1u_1 + m_2u_2 = (m_2 + m_1)v \quad \text{if they stick together}$ Change in p_1 = change in p_2 $m_1u_1 - m_1v_1 = m_2v_2 - m_2u_2$	
5.4	I can use Newton's third law to explain the motion of objects involved in interactions.	

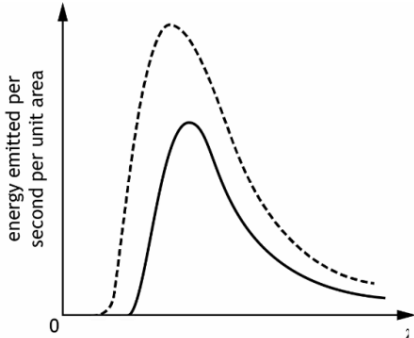
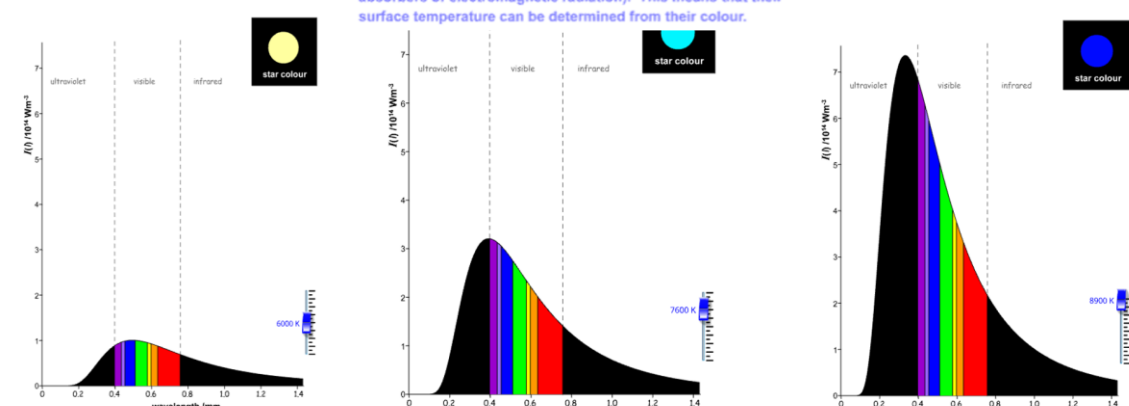
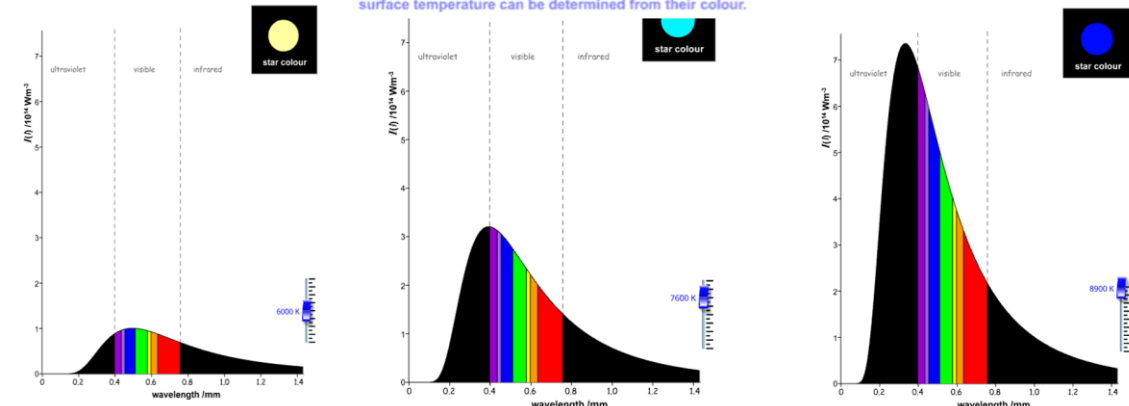
No	CONTENT	✓ x
5.5	I can draw and interpret force-time graphs involving interacting objects. For force-time graphs: area under graph $= Ft$ $= \Delta p$ (change in momentum) $= \text{impulse}$ Impulse = area under the graph $= \frac{1}{2} \times 12 \times 5 = 30 \text{ N s.}$ Note the 12N is the peak Force and not the force you calculate which is the average Force. In reality a force-time graph is usually a bell curve. 	
5.6	the impulse of a force is equal to the area under a force-time graph and is equal to the change in momentum of an object involved in the interaction.	
5.7	 The area under both these graphs should be the same as they equal the change in momentum. Safety devices often use the principle of increasing the time to stop which reduces your average Force -which is what harms you. Eg you don't usually die every time you come off the motorway and come to a stop at the junction, you stop over a long distance. It is when you hit something and stop very quickly that there is a problem	
5.8	I can use appropriate relationships to solve problems involving mass, change in velocity, average force and duration of the force for an object involved in an interaction. I've always encouraged the use of $Ft = m(v - u)$ but remember this is just a rearrangement of Newton's second Law $F = ma$, so if you are more comfortable using that formula then do: who am I to judge!	
6.	Gravitation	
Eq	$d = \bar{v}t, s = \bar{v}t; s = \frac{1}{2}(u + v)t; v = u + at \quad s = ut + \frac{1}{2}at^2 \quad v^2 = u^2 + 2as$ $F = \frac{Gm_1m_2}{r^2}$	
6.1	I can use the equation $F = \frac{Gm_1m_2}{r^2}$ Remember r is the radius, or mean distance from the centre of an object to the centre of the other object. If the height above the planet etc is given you must add the radius of the planet, if it is the radius between two planets, or the moon and planet, or Sun and planet then the distance is measured from the centre of mass.	

No	CONTENT	✓ x
6.2	<i>I can give a description of an experiment to measure the acceleration of a falling object.</i>	
6.3	the horizontal motion and the vertical motion of a projectile are independent of each other.	
6.4	satellites are in free fall around a planet/star.	
6.5	I can resolve the initial velocity of a projectile into horizontal and vertical components and their use in calculations. <i>If the angle is given to the horizontal your vertical component = $R \sin \theta$ If the angle is given to the horizontal your horizontal component = $R \cos \theta$ Or [Rec(R,angle)] gives X= horizontal, Y= vertical</i>	
6.6	I can use resolution of vectors, vector addition, and appropriate relationships to solve problems involving projectiles.	
6.7	I can use Newton's Law of Universal Gravitation to solve problems involving force, masses and their separation. $F = \frac{Gm_1m_2}{r^2}$ <i>Beware a typical mistake is to forget the square the radius. If you are given the height of a satellite from the surface, don't forget to add the radius of the planet on to r. If it is the mean distance between eg the Earth and Sun in the data sheet, this already has the radii included!</i>	

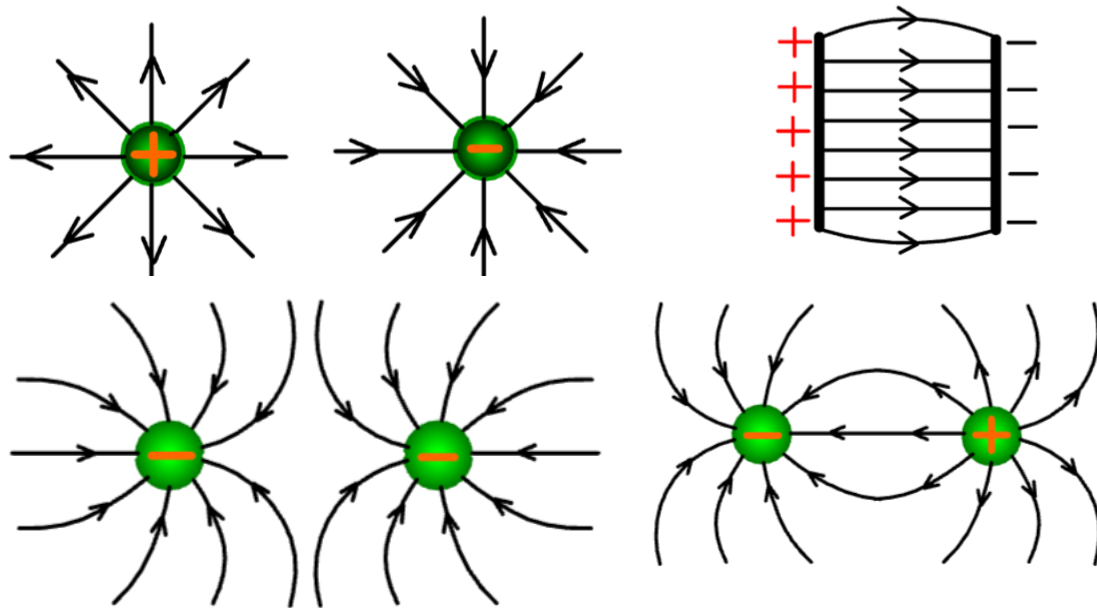
7.	Special relativity	
Eq	$l' = l \sqrt{1 - \frac{v^2}{c^2}} \quad t' = \frac{t}{\sqrt{1 - \frac{v^2}{c^2}}}$	
7.1	the speed of light in a vacuum is the same for all observers.	
7.2	measurements of space, time and distance for a moving observer are changed relative to those for a stationary observer, giving rise to time dilation and length contraction.	
7.3	I can use appropriate relationships to solve problems involving time dilation, length contraction and speed. <i>The person with the measuring tape or watch in the same inertial frame of reference as the object being measured has the correct value. Those observing from a different inertial frame of reference are measuring t' or l' BTW no need to change the units of t and l into s and m as it is a ratio, the units will be the same as the original units.</i>	

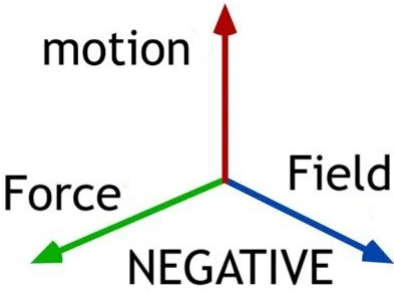
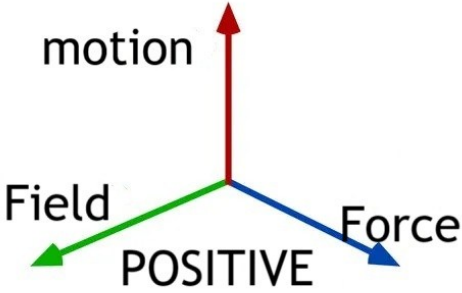
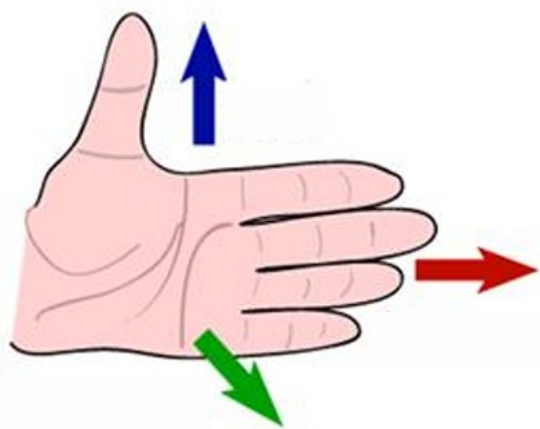
8.	The expanding Universe	
Eq	$f_o = f_s \left(\frac{v}{v \pm v_s} \right) \quad f_{\text{observed}} = f_{\text{source}} \frac{v}{[v + v_{\text{source}}]} \quad v = H_o d \quad z = \frac{v}{c}$ $z = \frac{\lambda_{\text{observed}} - \lambda_{\text{rest}}}{\lambda_{\text{rest}}}$	
8.1	the Doppler effect causes shifts in wavelengths of sound and light.	

No	CONTENT	✓ x
	Frequency increasing as an object making a sound moves toward the observer Statement that there are more wavefronts per second (arriving at the microphone/person/detector). OR The wavefronts (arriving at the microphone/person/detector) are closer together. OR Diagram showing wavefronts closer together ahead of the vehicle and further apart behind it. Don't draw the car, just an arrow! 	
8.2	I can use appropriate relationship to solve problems involving the observed frequency, source frequency, source speed and wave speed. $f_o = f_s \left(\frac{v}{v \pm v_s} \right)$ Start with this equation if it is moving towards or away as that gets one mark in the bag! If the object is coming <u>Towards</u>, <u>Take</u> away, if the object is going <u>AWAY</u>, <u>Add</u>	
8.3	the light from objects moving away from us is shifted to longer wavelengths (redshift).	
8.4	The redshift of a galaxy is the change in wavelength divided by the emitted wavelength. For slowly moving galaxies, redshift is the ratio of the recessional velocity of the galaxy to the velocity of light.	
8.5	I can use appropriate relationships to solve problems involving redshift, observed wavelength, emitted wavelength, and recessional velocity $z = \frac{\lambda_o - \lambda_r}{\lambda_r} \text{ or } \lambda_r = \frac{\lambda_o}{z + 1} \text{ or } \lambda_o = (z \times \lambda_r) + \lambda_r$ This equation can be hard to rearrange so you might want to learn the alternatives, well for λ_r anyway	
8.6	I can use appropriate relationship to solve problems involving the Hubble constant, the recessional velocity of a galaxy and its distance from us. $z = \frac{\lambda_o - \lambda_r}{\lambda_r} = \frac{v}{c} = \frac{H_0 d}{c}$ This is often presented as a multi-stage problem	
8.7	Hubble-Lemaître Laws law allows us to estimate the age of the Universe.	
8.8	measurements of the velocities of galaxies and their distance from us lead to the theory of the expanding Universe.	
8.9	the mass of a galaxy can be estimated by the orbital speed of stars within it.	
8.10	evidence supporting the existence of dark matter comes from estimations of the mass of galaxies.	
	Therefore combining 8.9 and 8.10 orbital speed of stars within a galaxy supports the idea of the existence of dark matter.	
8.11	evidence supporting the existence of dark energy comes from the accelerating rate of expansion of the Universe.	

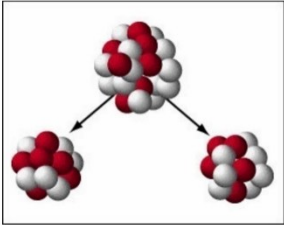
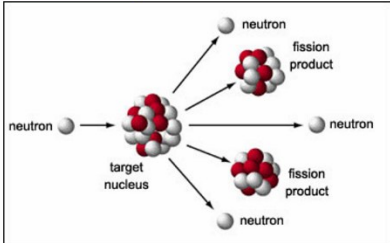
No	CONTENT	✓ x
8.12	I know that the temperature of stellar objects is related to the distribution of emitted radiation over a wide range of wavelengths.  2 Peak wavelength less. (1) Line added should always be above original line. (1)	
8.13	the peak wavelength of this distribution is shorter for hotter objects than for cooler objects. Stars effectively behave like black-bodies, (perfect radiators and absorbers of electromagnetic radiation). This means that their surface temperature can be determined from their colour.  Note if the x-axis was frequency these graphs would be flipped along the vertical axis. Please note the units of wavelength are incorrect on this graph and should be μm.	
8.14	hotter objects emit more radiation per unit surface area per unit time than cooler objects. Stars effectively behave like black-bodies, (perfect radiators and absorbers of electromagnetic radiation). This means that their surface temperature can be determined from their colour.  Note if the x-axis was frequency these graphs would be flipped along the vertical axis.	
8.15	evidence supporting the big bang theory and subsequent expansion of the Universe: cosmic microwave background radiation, the abundance of the elements hydrogen and helium, the darkness of the sky (Olbers' paradox) and the large number of galaxies showing redshift rather than blueshift.	

1.6 PARTICLES AND WAVES

No	CONTENT	✓ x
9.	Forces on charged particles	
Eq	$W = QV$ $E_k = \frac{1}{2}mv^2$	
9.1	charged particles experience a force in an electric field.	
9.2	electric fields exist around charged particles and between charged parallel plates.	
9.3	I can sketch electric field patterns for single-point charges, systems of two-point charges and between two charged parallel plates (ignore end effects). 	
9.4	I can determine the direction of movement of charged particles in an electric field. A positive particle will be attracted to the negative plate A negative particle will be attracted to the positive plate A neutral particle will travel through an electric field undeviated.	
9.5	voltage (potential difference) is the work done moving unit charge between two points	
9.6	I can solve problems involving the charge, mass, speed, and energy of a charged particle in an electric field and the potential difference through which it moves. <i>W by the field = E_k gained by charged particle</i> $QV = \frac{1}{2}mv^2$	
9.7	A moving charge produces a magnetic field.	

No	CONTENT	✓ x
9.8	I can determine the direction of the force on a charged particle moving in a magnetic field for negative and positive charges using the slap rule or other method.    Different colour scheme sorry! LEFT HAND Blue= direction of the particle Red = magnetic field (N to S) Green is the motion of a negative particle, and the backhand is the motion of a positive particle. Works for positive and negative and avoids arthritis in older life!	
9.9	I know the basic operation of particle accelerators in terms of acceleration by electric fields, deflection by magnetic fields and high-energy collisions of charged particles to produce other particles. In a particle accelerator the electric field accelerates the charged particle <i>$Ew \text{ by the field} = Ek \text{ gained by charged particle}$</i> $QV = \frac{1}{2} m v^2$ In a particle accelerator the magnetic field alters the direction of the charged particle When these particles are smashed together new particles are produced.	
10.	Standard Model	
10.1	The Standard Model is a model of fundamental particles and interactions.	
	Fundamental particles are not composed of other particles.	

No	CONTENT	✓ x
10.4	Evidence for the existence of quarks comes from high-energy collisions between electrons and nucleons, carried out in particle accelerators.	
10.5	In the Standard Model, every particle has an antiparticle.	
10.6	The production of energy in the annihilation of particles is evidence for the existence of antimatter	
10.7	beta decay was the first evidence for the neutrino.	
10.8	I know the equation for β^- decay above (β^+ decay not required) ${}_0^1n \rightarrow {}_1^1p + {}_{-1}^0e + \bar{\nu}_e$	
10.9	fermions, the matter particles, consist of quarks (six types: up, down, strange, charm, top, bottom) and leptons (electron, muon and tau, together with their neutrinos).	
10.10	hadrons are composite particles made of quarks.	
10.11	baryons are made of three quarks.	
10.12	mesons are made of quark-antiquark pairs.	
10.13	the force-mediating particles are bosons: photons (electromagnetic force), W- and Z-bosons (weak force), and gluons (strong force).	

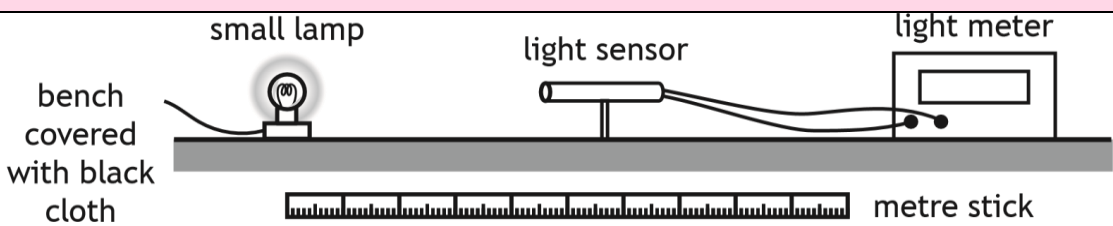
11.	Nuclear reactions	
Eq	$E = mc^2$	
a)	I can use nuclear equations to describe radioactive decay, fission (spontaneous and induced), with reference to mass and energy equivalence. Spontaneous the reaction occurs randomly but with no other input. Induced the reaction requires a neutron to start it off (induced reactions required in power station for control)  Figure 14: Spontaneous fission  Figure 15: Induced fission ${}_0^1n + {}_{92}^{238}\text{U} \rightarrow {}_{56}^{145}\text{Ba} + {}_{36}^{94}\text{Kr}$ ${}_0^1n + {}_{92}^{235}\text{U} \rightarrow {}_{42}^{98}\text{Mo} + {}_{54}^{136}\text{Xe} + 2{}_0^1n + 4{}_{-1}^0e$ ${}_{92}^{239}\text{U} \rightarrow {}_{93}^{239}\text{Np} + {}_{-1}^0e$ In these examples the first two equations show induced fission as a neutron is required to start the reaction The last one shows spontaneous fission (which is also beta decay)	

No	CONTENT	✓ x
	<u>Mass Before</u> ${}_{92}^{235}\text{U}$ $3.90088 \times 10^{-25} \text{ kg}$ ${}_0^1\text{n}$ $1.6749 \times 10^{-27} \text{ kg}$ Total $3.917629 \times 10^{-25} \text{ kg}$ <u>Mass after</u> ${}_{42}^{98}\text{Mo}$ $1.6249 \times 10^{-25} \text{ kg}$ ${}_{54}^{136}\text{Xe}$ $2.2556 \times 10^{-25} \text{ kg}$ $2 {}_0^1\text{n}$ $3.3498 \times 10^{-27} \text{ kg}$ $4 {}_{-1}^0\text{e}$ $3.32 \times 10^{-30} \text{ kg}$ Total $3.914031 \times 10^{-25} \text{ kg}$ mass change = mass before - mass after mass change = $3.917629 \times 10^{-25} \text{ kg} - 3.914031 \times 10^{-25} \text{ kg}$ mass change = $3.598 \times 10^{-28} \text{ kg}$ energy equivalence: $E = mc^2$ $E = 3.598 \times 10^{-28} \times (3 \times 10^8)^2$ $E = 3.598 \times 10^{-28} \times 9 \times 10^{16}$ $E = 3.24 \times 10^{-11} \text{ J}$	

No	CONTENT	✓ x										
b)	I can use nuclear equations to describe fusion reactions, with reference to mass and energy equivalence.											
	${}^2_1\text{H} + {}^3_1\text{H} \rightarrow {}^4_2\text{He} + {}^1_0\text{n}$											
	The masses of the particles involved in the reaction are shown in the table.											
	<table><tr><th>Particle</th><th>Mass (kg)</th></tr><tr><td>${}^2_1\text{H}$</td><td>3.3436×10^{-27}</td></tr><tr><td>${}^3_1\text{H}$</td><td>5.0083×10^{-27}</td></tr><tr><td>${}^4_2\text{He}$</td><td>6.6465×10^{-27}</td></tr><tr><td>${}^1_0\text{n}$</td><td>1.6749×10^{-27}</td></tr></table>	Particle	Mass (kg)	${}^2_1\text{H}$	3.3436×10^{-27}	${}^3_1\text{H}$	5.0083×10^{-27}	${}^4_2\text{He}$	6.6465×10^{-27}	${}^1_0\text{n}$	1.6749×10^{-27}	
	Particle	Mass (kg)										
	${}^2_1\text{H}$	3.3436×10^{-27}										
	${}^3_1\text{H}$	5.0083×10^{-27}										
	${}^4_2\text{He}$	6.6465×10^{-27}										
	${}^1_0\text{n}$	1.6749×10^{-27}										
	$m_{\text{before}} = 3.3436 \times 10^{-27} + 5.0083 \times 10^{-27}$ $= 8.3519 \times 10^{-27} \text{ (kg)}$ $m_{\text{after}} = 6.6465 \times 10^{-27} + 1.6749 \times 10^{-27}$ $= 8.3214 \times 10^{-27} \text{ (kg)}$	4										
$\Delta m = 3.0500 \times 10^{-29} \text{ (kg)}$ (1)	$E = mc^2$ anywhere - 1 mark. If mass before and after not used to 5 significant figures from table then stop marking - maximum 1 mark for formula Arithmetic mistake can be carried forward Truncation error in mass before and/or mass after- maximum 1 mark for formula											
$E = mc^2$ (1) $= 3.0500 \times 10^{-29} \times (3.00 \times 10^8)^2$ (1) $= 2.75 \times 10^{-12} \text{ J}$ (1)	Sig figs: 2.7, 2.745, 2.7450 If finding $E = mc^2$ for each particle, then $E = mc^2$ (1) All substitutions (1) Subtraction (1) Final answer (1)											

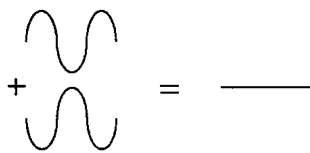
No	CONTENT	✓ x								
	${}^{241}_{95}\text{Am} \rightarrow {}^{237}_{93}\text{Np} + {}^4_2\text{He}$<table><tr><th>Particle</th><th>Mass (kg)</th></tr><tr><td>${}^{241}_{95}\text{Am}$</td><td>4.0028×10^{-25}</td></tr><tr><td>${}^{237}_{93}\text{Np}$</td><td>3.9363×10^{-25}</td></tr><tr><td>${}^4_2\text{He}$</td><td>6.6447×10^{-27}</td></tr></table> Mass before = 4.0028×10^{-25} (kg) Mass after = $3.9363 \times 10^{-25} + 6.6447 \times 10^{-27}$ Mass after = 4.002747×10^{-25} (kg) Mass lost = 5.3×10^{-30} (kg) (1) $E = mc^2$ (1) $E = 5.3 \times 10^{-30} \times (3.00 \times 10^8)^2$ (1) $E = 4.77 \times 10^{-13}$ J (1) 4 Accept: 4.8, 4.770, 4.7700 Check for correct substitutions of values in calculation of mass lost. If values are incorrect, maximum 1 mark for relationship, even if final answer is correct. $E = mc^2$ anywhere, 1 mark. If masses before and after not substituted to full significant figures as given in the table, then maximum 1 mark for relationship. Ignore inappropriate reference to mass defect. Arithmetic mistake can be carried forward through the response.	Particle	Mass (kg)	${}^{241}_{95}\text{Am}$	4.0028×10^{-25}	${}^{237}_{93}\text{Np}$	3.9363×10^{-25}	${}^4_2\text{He}$	6.6447×10^{-27}	
Particle	Mass (kg)									
${}^{241}_{95}\text{Am}$	4.0028×10^{-25}									
${}^{237}_{93}\text{Np}$	3.9363×10^{-25}									
${}^4_2\text{He}$	6.6447×10^{-27}									
c)	Use of an appropriate relationship to solve problems involving the mass loss and the energy released by a nuclear reaction. $E = mc^2$ <table><tr><td>(Some) mass (is lost and) converted to energy.</td><td>1</td><td> There must be an indication of mass being converted (or an equivalent term) to energy eg transformed, becomes, changed to. Do not accept: transferred. Mass is lost on its own (0) Mass defect is wrong physics (0) </td></tr></table>	(Some) mass (is lost and) converted to energy.	1	There must be an indication of mass being converted (or an equivalent term) to energy eg transformed, becomes, changed to. Do not accept: transferred. Mass is lost on its own (0) Mass defect is wrong physics (0)						
(Some) mass (is lost and) converted to energy.	1	There must be an indication of mass being converted (or an equivalent term) to energy eg transformed, becomes, changed to. Do not accept: transferred. Mass is lost on its own (0) Mass defect is wrong physics (0)								
d)	nuclear fusion reactors require charged particles at a very high temperature (plasma) which have to be contained by magnetic fields.									

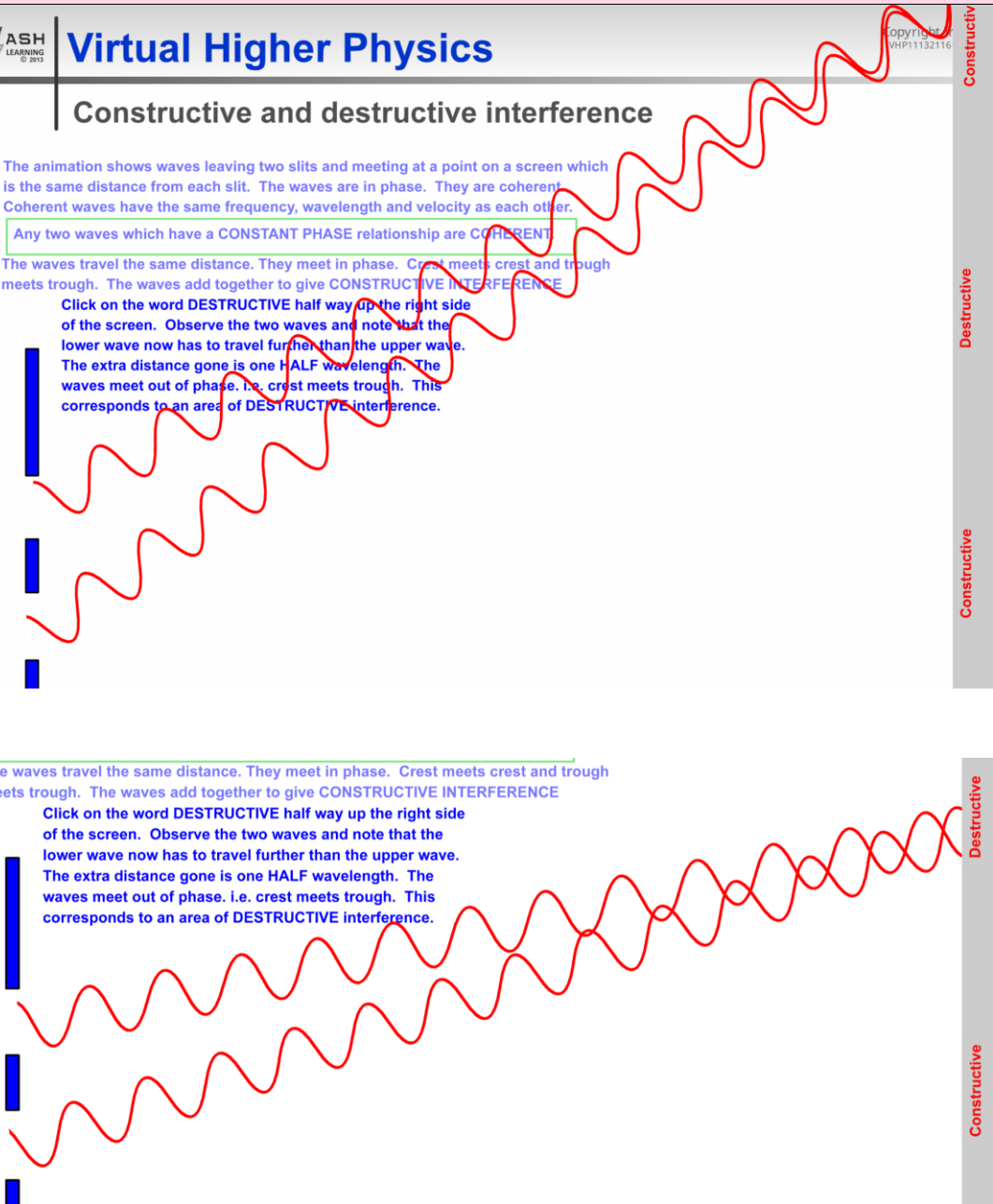
12.	Inverse square law	
Eq	$I = \frac{P}{A} \qquad I = \frac{k}{d^2} \qquad I_1 d_1^2 = I_2 d_2^2$	
a)	irradiance is the power per unit area incident on a surface.	
b)	I can use the equation $I = \frac{P}{A}$ to solve problems involving irradiance, the power of radiation incident on a surface and the area of the surface.	
c)	irradiance is inversely proportional to the square of the distance from a point source.	
d)		

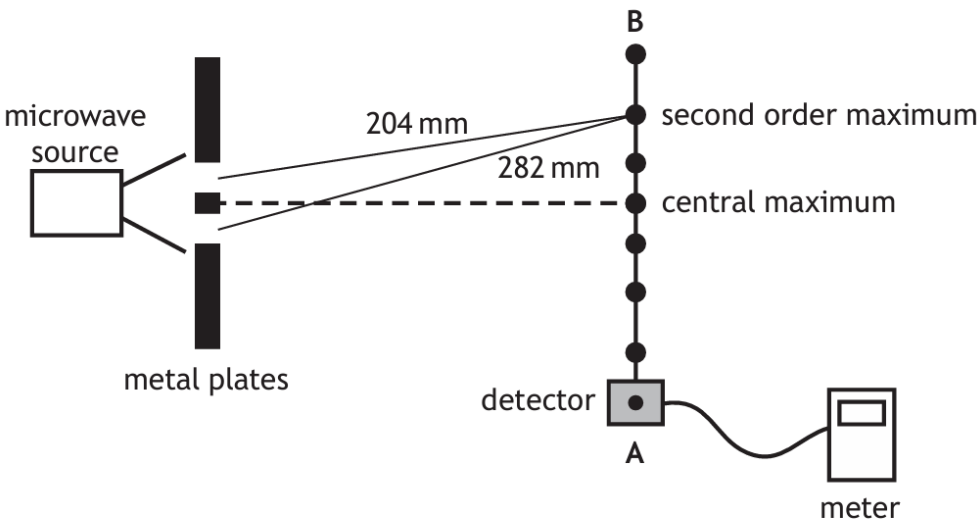
No	CONTENT	✓ x
	 How to make this experiment better • Smaller lamp / use point source. • Black cloth on bench / wear black clothing. • Greater range of distances. Smaller increments of distance. • Account for background light level eg Subtract background light level, • Tare/zero the light meter. Why is a laser not suitable for this experiment • Laser is not a point source. • Light from the laser does not conform to the inverse square law. • Laser beam does not diverge.	
e)	I can use $I = \frac{k}{d^2}$ and $I_1 d_1^2 = I_2 d_2^2$ to solve problems involving irradiance and distance from a point source of light. Don't let your 1s and 2s look like they are superscripts, you won't get any marks. Don't forget to square d! If the results are in a table you need to multiply the value of I by the value of d^2 and state that your results are all constant so that $Id^2 = k$	

13.	Wave Particle Duality	
eq	$E = hf$ $E = \frac{hc}{\lambda}$ $E_k = hf - hf_0$ $E_k = \frac{1}{2}mv^2$ and $v = f\lambda$	
a)	the photoelectric effect is evidence for the particle model of light.	
b)	photons of sufficient energy can eject electrons from the surface of materials (photoemission).	
c)	I can use $E = hf$ and $E = \frac{hc}{\lambda}$ to solve problems involving the frequency and energy of a photon.	
d)	the threshold frequency, f_0 is the minimum frequency of a photon required for photoemission.	
e)	The work function, W or hf_0 of a material is the minimum energy of a photon required to cause photoemission.	
f)	I can use $E_k = hf - hf_0$ $E_k = \frac{1}{2}mv^2$ and $v = f\lambda$ to solve problems involving the mass, maximum kinetic energy and speed of photoelectrons, the threshold frequency of the material, and the frequency and wavelength of the photons.	

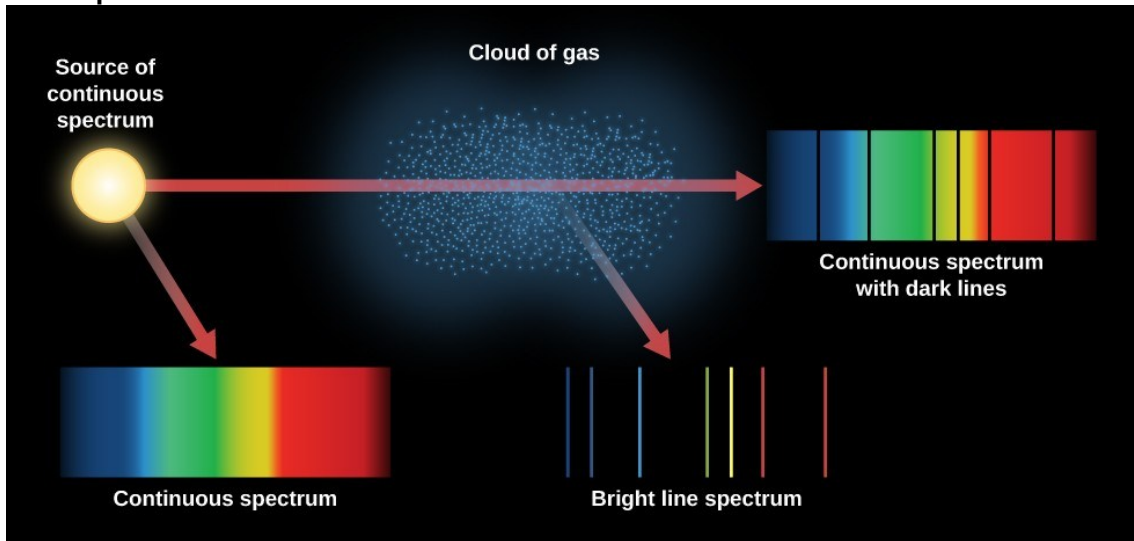
14.	Interference	
Eq	$path\ difference = m\lambda$ or $(m + \frac{1}{2})\lambda$ where $m = 0, 1, 2, \dots$ $d \sin\theta = m\lambda$	
a)	interference is evidence for the wave model of light.	
b)	coherent waves have a constant phase relationship. The waves from two sources have a constant phase	

No	CONTENT			✓ x
	The waves from the two sources have a constant phase relationship (and have the same frequency, wavelength, and velocity).	1	"In phase" is not sufficient	
c)	I can describe of the conditions for constructive and destructive interference in terms of the phase difference between two waves. Constructive interference- path difference is a whole no. of λ Waves <u>meet</u> in phase OR Crest <u>meets</u> crest OR Trough <u>meets</u> trough OR Path difference = $m\lambda$ Destructive interference path difference is a $\frac{1}{2}$ no. of λ Waves <u>meet</u> out of phase OR crest <u>meets</u> trough OR path difference = $(m+\frac{1}{2})\lambda$			
		1	Accept peak for crest Can be shown by diagram eg  Diagram must imply addition of two waves in phase	
				

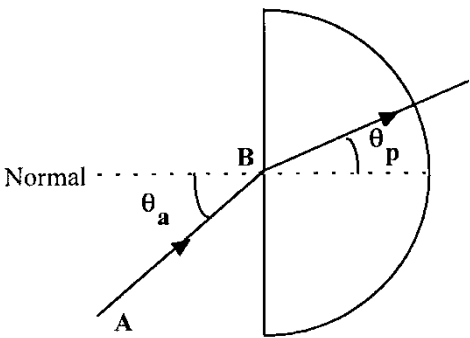
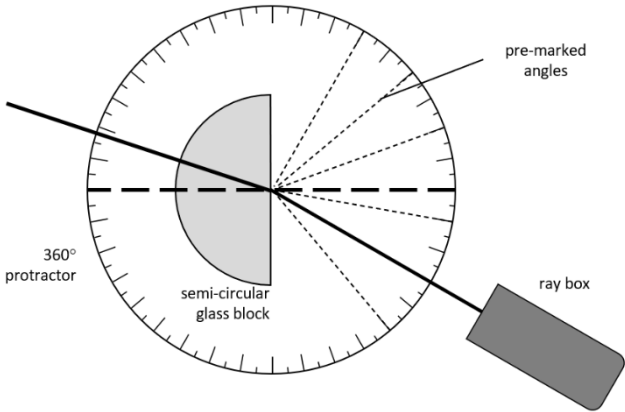
No	CONTENT	✓ x
	 Virtual Higher Physics Copyright © VHP11132116 Constructive and destructive interference The animation shows waves leaving two slits and meeting at a point on a screen which is the same distance from each slit. The waves are in phase. They are coherent. Coherent waves have the same frequency, wavelength and velocity as each other. Any two waves which have a CONSTANT PHASE relationship are COHERENT The waves travel the same distance. They meet in phase. Crest meets crest and trough meets trough. The waves add together to give CONSTRUCTIVE INTERFERENCE Click on the word DESTRUCTIVE half way up the right side of the screen. Observe the two waves and note that the lower wave now has to travel further than the upper wave. The extra distance gone is one HALF wavelength. The waves meet out of phase. i.e. crest meets trough. This corresponds to an area of DESTRUCTIVE interference.  The waves travel the same distance. They meet in phase. Crest meets crest and trough meets trough. The waves add together to give CONSTRUCTIVE INTERFERENCE Click on the word DESTRUCTIVE half way up the right side of the screen. Observe the two waves and note that the lower wave now has to travel further than the upper wave. The extra distance gone is one HALF wavelength. The waves meet out of phase. i.e. crest meets trough. This corresponds to an area of DESTRUCTIVE interference.	
d)	maxima are produced when the path difference between waves is a whole number of wavelengths	
e)	minima are produced when the path difference between waves is an odd number of half-wavelengths respectively.	
f)	I can use <i>path difference</i> = $m\lambda$ or $(m + \frac{1}{2})\lambda$ where $m = 0, 1, 2, \dots$ to solve problems involving the path difference between waves, wavelength and order number.	

No	CONTENT	✓ x
	A student carries out an experiment to measure the wavelength of microwave radiation. Microwaves pass through two gaps between metal plates as shown.  As the detector is moved from A to B, a series of maxima and minima are detected. Path Difference = $m\lambda$ (1) $0.282 - 0.204 = 2 \times \lambda$ (1) $\lambda = 0.0390\text{m}$ (1) (39 mm)	
g)	I can use $d \sin\theta = m\lambda$ to solve problems involving grating spacing, wavelength, order number and angle to the maximum. Try 2019 ppq question 10 Try 2022 ppq question 10	

15.	Spectra	
Eq	$E_2 - E_1 = hf$ and $E = hf$	
a)	I have knowledge of the Bohr model of the atom. A (central) positively charged nucleus. (Negatively charged) electrons in (discrete) energy levels/shells (orbiting the nucleus, not radiating energy.) When an electron moves from one state to another, the energy lost or gained is done so ONLY in very specific amounts of energy. Each energy jump results in the release or absorption of energy of specific wavelengths giving line in a spectrum is produced when an electron moves from one energy level/orbit/shell to another.	
b)	I can explain the Bohr model of the atom using the terms <i>ground state</i> , <i>energy levels</i> , <i>ionisation</i> and <i>zero potential energy</i> .	
c)	I know the mechanism of production of line emission spectra, continuous emission spectra and absorption spectra in terms of electron energy level transitions.	
d)	I can use $E_2 - E_1 = hf$ and $E = hf$ to solve problems involving energy levels and the frequency of the radiation emitted/absorbed.	

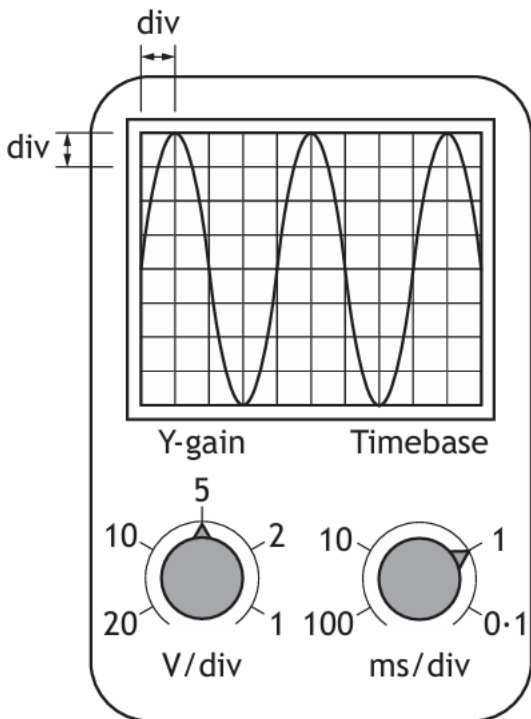
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e)	I know that the absorption lines (Fraunhofer lines) in the spectrum of sunlight provide evidence for the composition of the Sun's outer atmosphere.  The Fraunhofer lines are a set of dark absorption lines observed in the optical spectrum of the Sun. These lines are formed when light from the Sun's central core (photosphere) passes through the cooler outer atmosphere (chromosphere). The atoms and molecules in the chromosphere absorb specific wavelengths of light, resulting in the characteristic dark lines.	

16.	Refraction	
Eq	$n = \frac{\sin \theta_1}{\sin \theta_2} = \frac{\lambda_1}{\lambda_2} = \frac{v_1}{v_2} \quad \text{and} \quad v = f\lambda \quad \text{and} \quad \sin \theta_c = \frac{1}{n}$	
a)	I can define absolute refractive index of a medium as the ratio of the speed of light in a vacuum to the speed of light in the medium .	
b)	I can use $n = \frac{\sin \theta_1}{\sin \theta_2}$ to solve problems involving absolute refractive index, the angle of incidence and the angle of refraction.	
c)	<i>I can describe an experiment to determine the refractive index of a medium.</i>	

No	CONTENT	✓ x
	  - Shine the ray into the block at the normal - Record the angle of incidence and the angle of refraction. - Move the ray box to a new premarked angle - Plot a graph of $\sin \theta_{\text{air}} / \sin \theta_{\text{glass}}$, the gradient is the refractive index. - Taking angles either side of the normal reduces the likelihood of a systematic uncertainty due to the normal not being perpendicular to the block.	
d)	I can use $\frac{\sin \theta_1}{\sin \theta_2} = \frac{\lambda_1}{\lambda_2} = \frac{v_1}{v_2}$ and $v = f\lambda$ to solve problems involving the angles of incidence and refraction, the wavelength of light in each medium, the speed of light in each medium, and the frequency, including situations where light is travelling from a more dense to a less dense medium. Remember frequency remains the same in the material and in the air.	
e)	refractive index of a medium increases as the frequency of incident radiation increases.	
f)	critical angle is the angle of incidence which produces an angle of refraction of 90° .	
g)	total internal reflection occurs when the angle of incidence is greater than the critical angle.	
h)	$\sin \theta_c = \frac{1}{n}$ I can use $\frac{1}{n}$ to solve problems involving critical angle and absolute refractive index.	

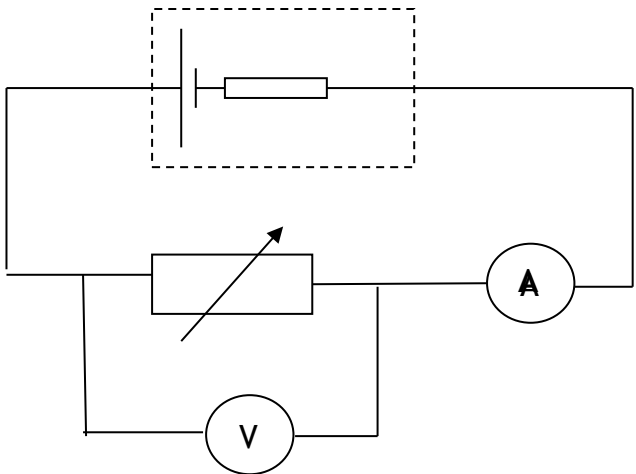
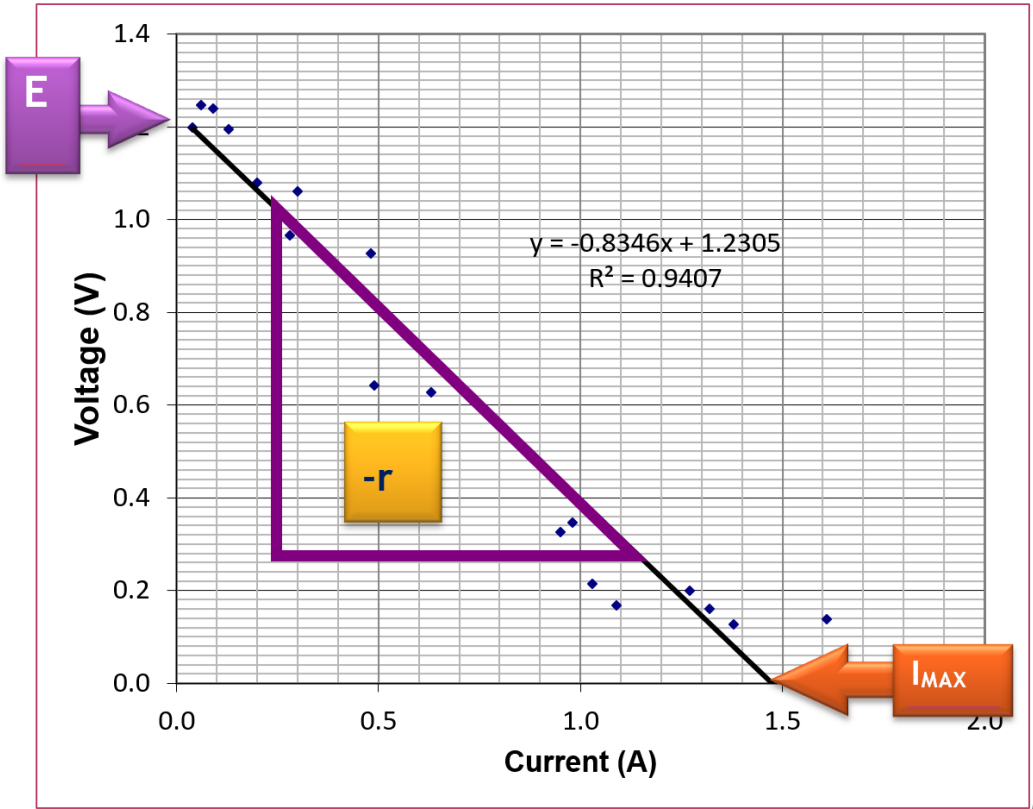
1.7 ELECTRICITY

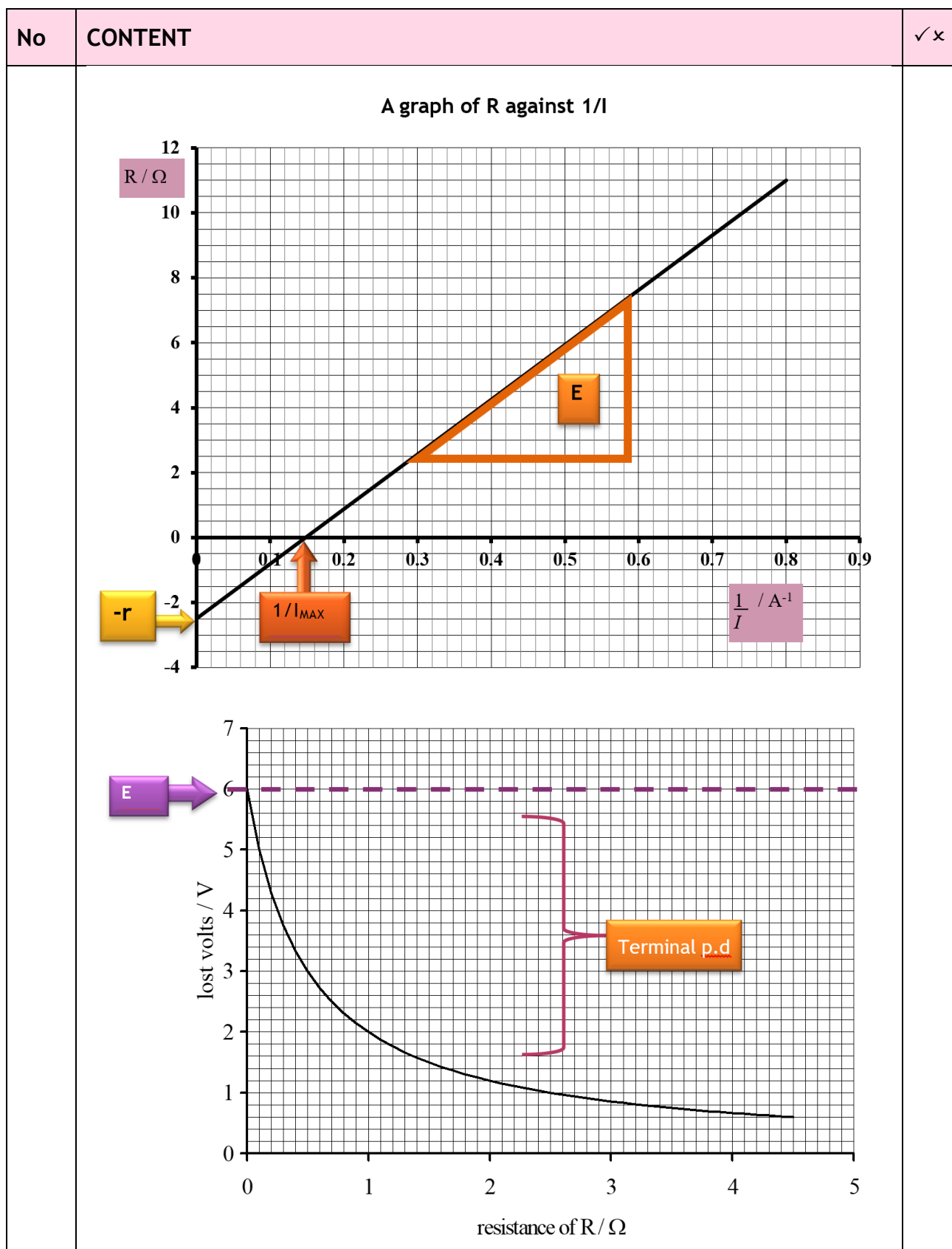
No	CONTENT	✓ x
17.	Monitoring and Measuring A.C.	
eq	$T = \frac{1}{f} \quad V_{rms} = \frac{V_{peak}}{\sqrt{2}} \quad I_{rms} = \frac{I_{peak}}{\sqrt{2}}$	
a)	an A.C. is a current which changes direction and instantaneous value with time. D.C is a direct current the charges flow in one direction only	
b)	I can use $V_{rms} = \frac{V_{peak}}{\sqrt{2}} \quad I_{rms} = \frac{I_{peak}}{\sqrt{2}}$ to solve problems involving peak and r.m.s. values.	

No	CONTENT	✓ x
c)	I can determine the frequency, peak voltage and r.m.s. values from graphical data.  1. Count the number of squares for 1 wave. 2. Multiply the number of squares for 1 wave by the time base setting, giving T. 3. Find frequency using $f = \frac{1}{T}$ (Time setting will be in ms or μs. DON'T FORGET TO CHANGE IT!!) 4 squares = one wave Each wave is 1 ms (read off the timebase setting)	
d)	I can use $T = \frac{1}{f}$ to determine the frequency.	

18.	Current, potential difference, power and resistance	
eq	$V = IR$ $P = IV = I^2 R = \frac{V^2}{R}$ $R_T = R_1 + R_2 + \dots$	
Eq	$\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \dots$ $V_2 = \left(\frac{R_2}{R_1 + R_2} \right) V_s$ $\frac{V_1}{V_2} = \frac{R_1}{R_2}$	
a)	I can use relationships involving potential difference, current, resistance and power to analyse circuits even those that may involve several steps in the calculations.	
b)	I can correctly use calculations involving potential dividers circuits.	

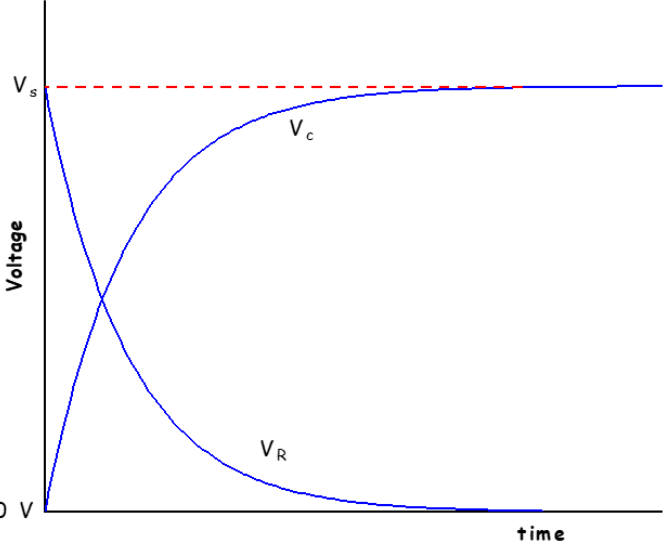
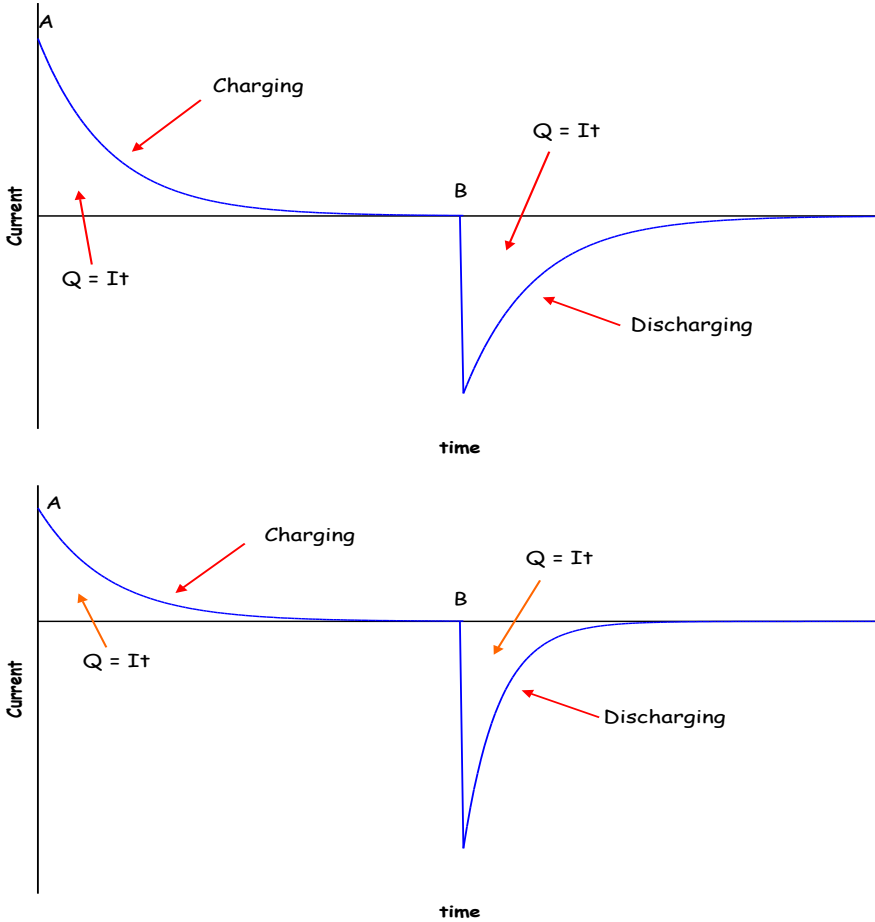
19.	Electrical sources and internal resistance	
eq	$E = V + Ir$ $V = IR$	
a)	I can correctly use and explain the terms electromotive force (E.M.F), internal resistance, lost volts, terminal potential difference (t.p.d) ideal supplies, short circuits and open circuits.	
b)	I can use $E = V + Ir$ and $V = IR$ to solve problems involving EMF, lost volts, t.p.d., current, external resistance, and internal resistance.	

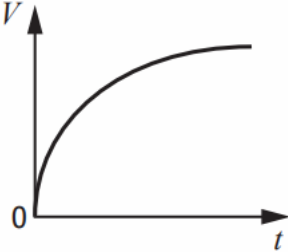
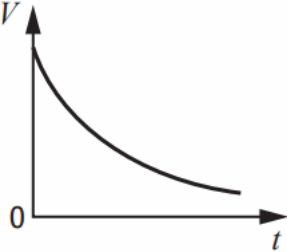
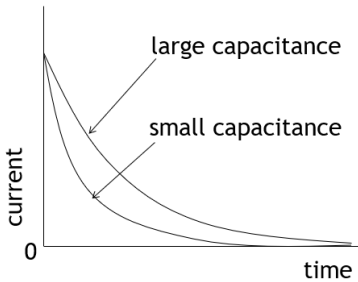
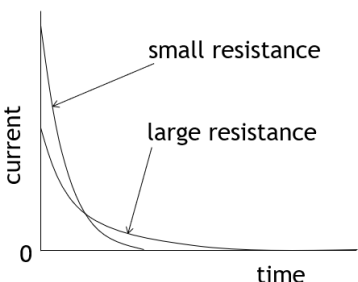
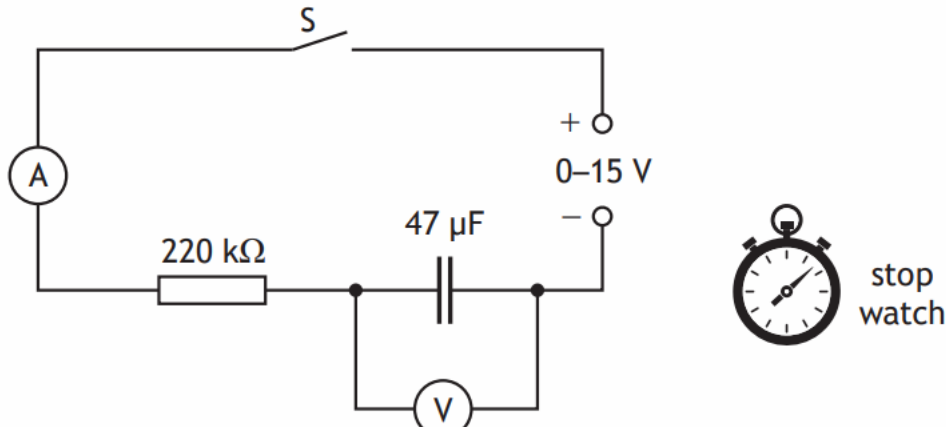
No	CONTENT	✓ x
c)	<i>I can describe of an experiment to measure the EMF and internal resistance of a cell.</i> 	
d)	I can determine electromotive force, internal resistance and short circuit current using graphical analysis. 	

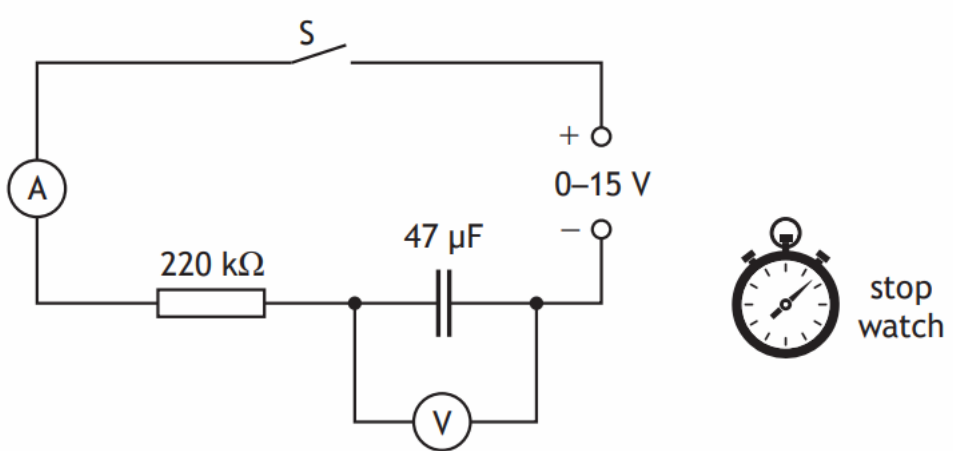


No	CONTENT	✓ x
	In the diagram above take a value of R and the corresponding I and that gives you the terminal p.d. The short circuit current is the value on the y-axis when $R=0\ \Omega$. For this graph the EMF needs to be given so this graph can be used to find the internal resistance only.	

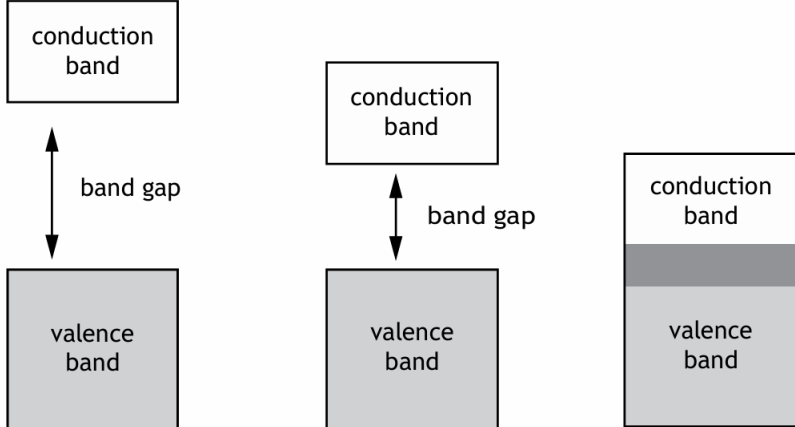
20.	Capacitors	
	$C = \frac{Q}{V}$ $Q = It$	
eq	$E = \frac{1}{2} QV = \frac{1}{2} CV^2 = \frac{1}{2} \frac{Q^2}{C}$ as soon as you are allowed in your exam, write on your relationships sheet by these equations (for energy STORED on a capacitor only)	
a)	a capacitor of 1 farad will store 1 coulomb of charge when the potential difference across it is 1 volt.	
b)	I can use the equation $C=Q/V$ to solve problems involving capacitance, charge and potential difference.	
c)	I can use the equation $Q=It$ to determine the charge stored on a capacitor for a constant charging current.	
d)	the total energy stored in a charged capacitor is equal to the area under a charge-potential difference graph.	

No	CONTENT	✓ x
	 To find the V across capacitor or V across the resistor at any point in time remember $V_s = V_R + V_C$. Eg if $V_s = 12V$ and you know the voltage across one of the other components you can subtract this value from 12V to find the voltage across the other component.	
e)	I can use $E = \frac{1}{2} QV = \frac{1}{2} CV^2 = \frac{1}{2} \frac{Q^2}{C}$ to solve problems involving energy, charge, capacitance, and potential difference.	
f)	I know the variation of current with time for both charging and discharging cycles of a capacitor in an RC circuit (charging and discharging curves). Charging and discharging through the same resistor max current at charging is the same as max current at discharging 	

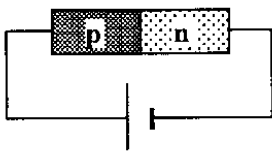
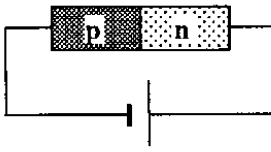
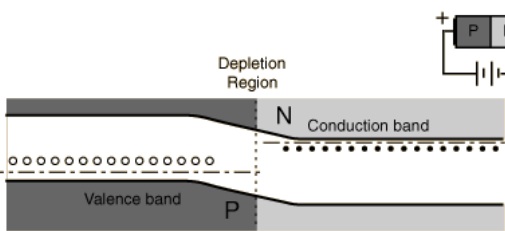
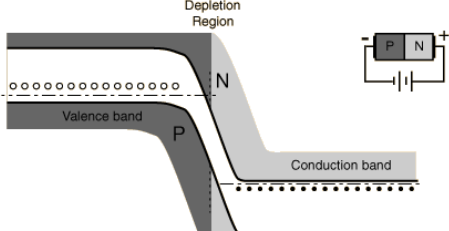
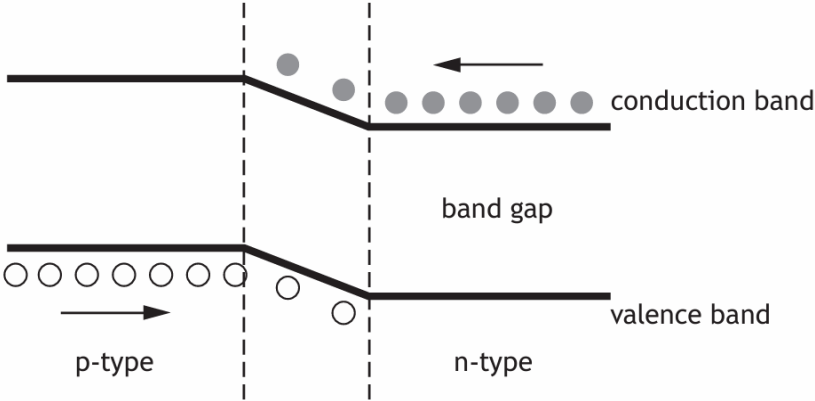
No	CONTENT	✓ x
	In the above graph the capacitor is discharging through a smaller resistance so the initial discharge current is greater than the charging current but the time for discharging is less than the time for charging	
g)	I know the variation of potential difference with time for both charging and discharging cycles of a capacitor in an RC circuit (charging and discharging curves).   Charging (max $V=V_s$) Discharging (Max $V=V_s$)	
h)	I know the effect of resistance and capacitance on charging and discharging curves in an RC circuit. Greater the resistance Greater the capacitance The longer it takes for a capacitor to charge It does not depend on the voltage of the supply. The effect of capacitance on charging current  The effect of resistance on charging current  (remember the area under the graph which equals charge stored ought to be the same) If the resistance is greater the charging time is longer but the initial current is less	
i)	<i>I can describe experiments to investigate the variation of current in a capacitor and voltage across a capacitor with time, for the charging and discharging of capacitors</i> For V against t 	

No	CONTENT	✓ x
	For V against t  (Close the switch and) take readings on voltmeter at (regular) time intervals (1) Plot a graph of voltage against time (1) For I against t (Close the switch and) take readings on ammeter at (regular) time intervals (1) Plot a graph of current against time (1)	

21.	Semiconductors and p-n junctions	
a)	I know and can explain the terms conduction band and valence band.	

No	CONTENT	✓ x
b)	solids can be categorised into conductors, semiconductors or insulators by their band structure and their ability to conduct electricity. Every solid has its own characteristic energy band structure. For a solid to be conductive, both free electrons and accessible empty states must be available. The diagrams below show the distributions of the valence and conduction bands of materials classified as conductors, insulators and semiconductors. Shaded areas represent bands occupied by electrons. The band gap is also indicated.  Material 1 Insulator Material 2 semiconductor Material 3 conductor	
c)	I can explain qualitatively the electrical properties of conductors, insulators and semiconductors using the electron population of the conduction and valence bands and the energy difference between the conduction and valence bands. (Reference to Fermi levels is not required.) In an insulator the valence band is full, and there is a large band gap to the empty conduction band. Electrons don't have the energy to move into the conduction band In a conductor the conduction and valence bands overlap, both are partially filled, electrons can freely move between the two bands In a semiconductor there is a band gap, the gap is small, so only small amounts of energy are required to allow electrons from the valence band into the conduction band. ► Semiconductors are like insulators in that the valence band is full. However the gap between the two bands is small and at room temperature some electrons have enough energy to jump the gap and move from the valence to the conduction band. An increase in temperature increases the conductivity of a semiconductor.	
d)	the electrons in atoms are contained in energy levels. When the atoms come together to form solids, the electrons then become contained in energy bands separated by gaps.	

No	CONTENT	✓ x
	 You don't need to understand how or why this occurs. One atom has its electron shells but when you start adding atoms then the shells blur a little, until with a solid material these shells have combined to form bands.	
e)	for metals one or more bands are partially filled.	
f)	some metals have free electrons and partially filled valence bands, therefore they are highly conductive.	
g)	some metals have overlapping valence and conduction bands. Each band is partially filled and therefore they are conductive.	
h)	In an insulator, the highest occupied band (called the valence band) is full. The first unfilled band above the valence band is the conduction band. For an insulator, the gap between the valence band and the conduction band is large and at room temperature there is not enough energy available to move electrons from the valence band into the conduction band where they would be able to contribute to conduction. There is no electrical conduction in an insulator.	
i)	in a semiconductor, the gap between the valence band and conduction band is smaller (than in an insulator) and at room temperature there is sufficient energy available to move some electrons from the valence band into the conduction band allowing some conduction to take place. An increase in temperature increases the conductivity of a semiconductor.	
j)	During manufacture, semiconductors may be doped with specific impurities to increase their conductivity, resulting in two types of semiconductor: p-type and n-type. NB both n-type and p-type materials are neutrally charged as there is a proton in the nucleus for every electron in its shell.	
k)	when a semiconductor contains the two types of doping (p-type and n-type) in adjacent layers, a p-n junction is formed. There is an electric field in the p-n junction. The electrical properties of this p-n junction are used in a number of devices.	

No	CONTENT	✓ x
l)	Forward bias reduces the electric field; reverse bias increases the electric field in the p-n junction.  cell connected - positive end to p-type negative end to n-type Forward-biased  cell connected - negative end to p-type positive end to n-type Reverse-biased  p-n junction  p-n junction	
m)	 LEDs are forward biased p-n junction diodes that emit photons. The forward bias potential difference across the junction causes electrons to move from the conduction band of the n-type semiconductor towards the conduction band of the p-type semiconductor. Photons are emitted when electrons ‘fall’ from the conduction band into the valence band either side of the junction (Voltage applied causes) <u>electrons</u> to move towards <u>conduction band</u> of p-type/ away from n-type (towards the junction) (1) Electrons move/ drop from conduction band to valence band (1) <u>Photon</u> emitted (when electron drops) (1)	
n)	solar cells are p-n junctions designed so that a potential difference is produced when photons are absorbed. (This is known as the <u>photovoltaic effect</u>.) The absorption of photons provides energy to	

No	CONTENT	✓ x				
	‘raise’ electrons from the valence band of the semiconductor to the conduction band. The p-n junction causes the electrons in the conduction band to move towards the n-type semiconductor and a potential difference is produced across the solar cell. Explain how light gates produce a potential difference! <table><tr><td>Photovoltaic (effect)</td></tr><tr><td>Electrons gain/absorb energy from photons/light (1)</td></tr><tr><td>Electrons move from <u>valence band</u> to <u>conduction band</u> (1)</td></tr><tr><td>Electrons move towards n-type (semiconductor producing a potential difference). (1)</td></tr></table>	Photovoltaic (effect)	Electrons gain/absorb energy from photons/light (1)	Electrons move from <u>valence band</u> to <u>conduction band</u> (1)	Electrons move towards n-type (semiconductor producing a potential difference). (1)	
Photovoltaic (effect)						
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Electrons move towards n-type (semiconductor producing a potential difference). (1)						

Physical Quantity	Symbol	Unit	Unit Abb.
acceleration	a	metre per second per second	m s^{-2}
acceleration due to gravity	g	metre per second per second	m s^{-2}
amplitude	A	metre	m
angle	θ	degree	°
area	A	square metre	m^2
average speed	$\bar{v}$	metres per second	m s^{-1}
average velocity	$\bar{v}$	metres per second	m s^{-1}
capacitance	C	farad	F
change of speed	Δv	metre per second	m s^{-1}
change of velocity	Δv	metre per second	m s^{-1}
critical angle	θ_c	degree	°
current	I	ampere	A
displacement	s	metre	m
distance	D	metre, light year	m , ly
distance, depth, height	d or h	metre	m
electric charge	Q	coulomb	C
electric charge	Q or q	coulomb	C
electric current	I	ampere	A

Physical Quantity	Symbol	Unit	Unit Abb.
electric field strength	E	newton per coulomb volts per metre	N C^{-1} Vm^{-1}
electromotive force (e.m.f)	E or ε	volt	V
energy	E	joule	J
energy level	E_1, E_2	joule	J
final velocity	v	metre per second	m s^{-1}
force	F	newton	N
force, tension, upthrust, thrust	F	newton	N
frequency	f	hertz	Hz
frequency of source	f_s	hertz	Hz
fringe separation	Δx	metre	m
grating to screen distance	D	metre	m
gravitational field strength	g	newton per kilogram	N kg^{-1}
gravitational potential energy	E_p	joule	J
heat energy	E_h	joule	J
height, depth	h	metre	m
impulse	Ft	newton second kilogram metre per second	Ns kg m s^{-1}
initial speed	u	metre per second	ms^{-1}
initial velocity	u	metre per second	m s^{-1}
internal resistance	r	ohm	Ω
irradiance	I	watt per square metre	W m^{-2}
kinetic energy	E_k	joule	J
length	l	metre	m
mass	m	kilogram	kg
momentum	p	kilogram metre per second	kg m s^{-1}
number of photons per second per cross sectional area	N	-	-
observed wavelength	$\lambda_{\text{observed}}$	metre	m
peak current	I_{peak}	ampere	A
peak voltage	V_{peak}	volt	V
period	T	second	s
Planck's constant	h	joule second	Js

Physical Quantity	Symbol	Unit	Unit Abb.
potential difference	V	volt	V
potential energy	E_p	joule	J
power	P	watt	W
pressure	P or p	pascal	Pa
radius	r	metre	m
Redshift	Z	-	-
refractive index	n	-	-
relativistic length	l'	metre	m
relativistic time	t'	second	s
resistance	R	ohm	Ω
rest wavelength	λ_{rest}	metre	m
root mean square current	I_{rms}	ampere	A
root mean square voltage	V_{rms}	volt	V
slit separation	d	metre	m
specific heat capacity	c	joule per kilogram per kelvin	$\text{Jkg}^{-1}\text{K}^{-1}$
specific latent heat	l	joule per kilogram	Jkg^{-1}
speed of light in a vacuum	c	metre per second	m s^{-1}
speed, final speed	v	metre per second	ms^{-1}
speed, velocity, final velocity	v	metre per second	m s^{-1}
supply voltage	V_s	volt	V
temperature	T	degree Celsius	$^{\circ}\text{C}$
temperature	T	kelvin	K
threshold frequency	f_o	hertz	Hz
time	t	second	s
total resistance	R_t	ohm	Ω
velocity of observer	v_o	metre per second	m s^{-1}
velocity of source	v_s	metre per second	m s^{-1}
voltage	V	volt	V
voltage, potential difference	V	volt	V
volume	V	cubic metre	m^3
Wavelength	λ	metre	m
weight	W	newton	N

GRAPHING		
Axes appropriately labelled (quantity and units) and axes linearly scaled. (1) [Allow for axes starting at zero or broken axes or an appropriate value]. Data points plotted accurately. (1) Appropriate line of best-fit. (1)	3	If the origin is shown the scale must either be continuous, or the axis must be 'broken'. Otherwise, maximum 2 marks. If non-linear scale is used over the range of the data on either axis eg values from the table are used as the scale points, (0) marks. Do not penalise if candidates plot e against F. Accuracy of plotting should be easily checkable with the scale chosen. An appropriate scale to allow the accuracy of plotting to be checked must be linear over the range of the data.

2 UNCERTAINTIES

2.1 QUANTIFYING UNCERTAINTIES

1. Find the mean

$$\text{mean value} = \frac{\Sigma \text{results}}{\text{no. of observation}}$$

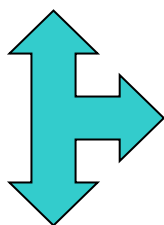
This is the best estimate of the “true” value but not necessary the “true” value



2. Find the approximate random uncertainty in the mean (absolute uncertainty)

$$\text{random uncertainty} = \frac{\text{max. value} - \text{min. value}}{\text{number of values}}$$

This can be written as $= \frac{\text{range}}{\text{no. of observation}}$ and it is sometimes referred to as *average deviation or absolute uncertainty*.



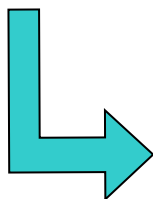
stop here and quote the result with an approx. random uncertainty

MEAN $\pm$ approx. random uncertainty (UNITS)

3. Find the percentage uncertainty.

$$\text{percentage uncertainty} = \frac{\text{approximately random uncertainty}}{\text{mean value}} \times 100\% =$$

$$\text{percentage uncertainty} = \frac{\frac{\text{range}}{n}}{\text{mean value}} \times 100\%$$



stop here and quote the result with a percentage uncertainty

MEAN (UNITS) $\pm$ percentage uncertainty (%)

Or (uncertainty in reading/reading) $\times$ 100%

2.2 SCALE READING UNCERTAINTY

[Content](#)

Analogue device = $\pm \frac{1}{2}$ scale division

Digital device = ± 1 in the last digit

2.3 OVERALL UNCERTAINTY IN AN EXPERIMENT

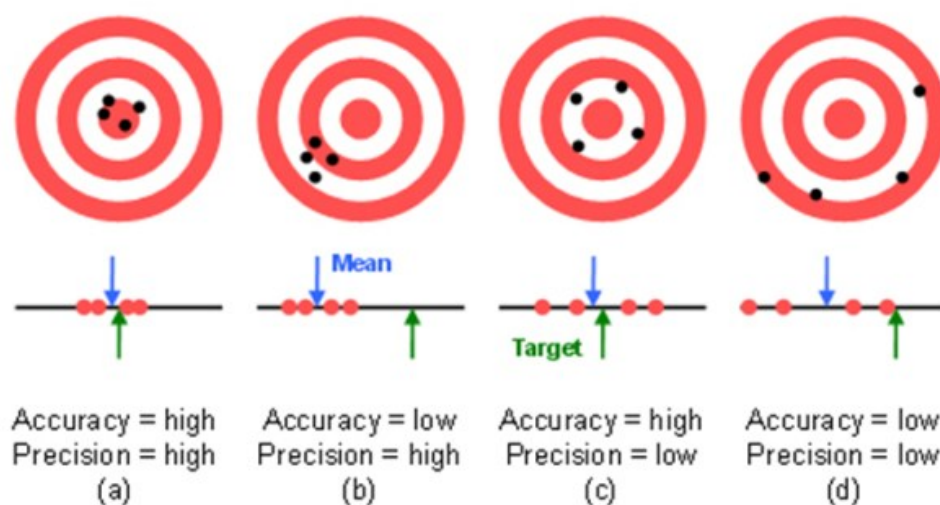
In an experiment, where more than one physical quantity has been measured, spot the quantity with the largest percentage uncertainty. This percentage uncertainty is often a good estimate of the percentage uncertainty in the final numerical result of the experiment.

eg if one measurement has an uncertainty of 3% and another has an uncertainty of 5%, then the overall percentage uncertainty in this experiment should be taken as 5%

When completing an experimental EVALUATION, always refer to the magnitude of the uncertainty to give an indication of how reliable your results are.

2.4 ACCURACY & PRECISION

Accuracy is **how close your answer is to the true value**. Precision is **how repeatable a measurement is**. Use the diagram below to remind you which is which.



<http://preview.tinyurl.com/lwanwoh>

In Physics you will often calculate an answer to a question that has a large number of significant figures or decimal places. Because it is highly unlikely that we need to know the answer that precisely. It is important to round off any answers that you find.

2.5 HOW MANY SIGNIFICANT FIGURES?

The simple rule is this: Your answer should have no more than the number of significant figures given in the question.

If different numbers in the question are given to a different number of significant figure you should use the number of significant figures in the value given to the smallest number of significant figures.

2.6 EXAMPLE

Question: A rocket motor produces 4,570N of thrust to a rocket with a mass of 7.0kg. What is the acceleration of the rocket?

The calculated answer to this question would be $652.8571429 \text{ ms}^{-2}$. However the least accurate value we are given in the question is the value of the mass. This is only given

You need to refer to the document General Marking Principles for guidance on how questions are marked.

https://www.sqa.org.uk/files_ccc/general-marking-principles-physics.pdf

Before you get in to the Higher Physics Course make sure you've looked over this material (there are laminated sheets in the Physics Dept).